

Contactless Position sensors for space mechanisms based on eddy current sensing

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PR1-M-0423-A

Public

05/02/2021

CTEC at a glance



CTEC's space heritage

 For more than 20 years, CTEC has been involved in various space missions, delivering products designed for severe environment conditions (vibrations, shocks, vacuum, humidity, wide thermal range including cryogenic).

Aerospace and Defence Heritage Flyer



MIDAS AFM for Rosetta





PAM30 specified by JPL for Psyche



Eddy current sensor (ECS) with printed circuit board (PCB) coils

- Eddy current sensor (ECS) technology, using printed circuit board (PCB) for printed coils.
- > PCB coils advantages:
- Low thickness.
- Complex designs capability
 - (multi-coils, multi-layers) -> differential measurement.
- Production repeatibility.
- Production cost.
- Mechanical integration.
- Spatialization.
- According to CTEC's experience, they provide both a good resolution/accuracy and a good robustness against temperature variations.
- > These sensors are available commercially off the shelf (COTS).
- They can be used for quick feasibility development and as a starting point for custom products delta designs.





> Typical accuracy achieved after conditio	nning	
Resolution (BW = 20 kHz) (1)	0.010	% FS (2)
Resolution (BW = 1 kHz)	0.003	% FS
Resolution (BW = 20 kHz), extended range (1000 μ m)	0.015	% FS
Resolution (BW =1 kHz), extended range (1000 μm)	0.005	% FS

ANNOTATIONS

(1) BW : Bandwidth

(2) FS : Full Scale

OPERATING ENVIRONMENT

PARAMETER	TYPICAL VALUE	UNIT
Operating temperature range	-25 +70	°C
Storage temperature range	-35 +100	°C



COTS Eddy current position sensor principle (distance measurement)











Inductance value is robust against T° variations







05/02/2021



Eddy current sensor (ECS) integrated in mechanisms

MEFISTO space mechanism

Actuators : APA120ML

- Stroke : 130µm @ 170V ; Blocked force : 1400N
- > Sensors : Eddy Current Sensors ECS
 - resolution : 10nm ; linearity 0.1% on 100µm





MEFISTO mechanism with its 2kg load

MEFISTO space mechanism

- > Close loop control
 - tracking error up to 20µm
 - speed error is less than 1%



Order, stroke & error of a foot versus time

> System performance

Tilt stroke	0.7 mrad	
Tip stroke	80µm	
Resonance frequencies	700-800 Hz	
Speed	0.5 mrad in 2 ms	
Sine Vibration level	20 g rms @ 100Hz	
Random Vibration level	15 g rms	
Dimensions	279×250×293 mm	
Mirror mass	730 gr	
Mirror size	220×96×23 mm	
Total mass	12.7 kg	

MEFISTO Performances



Eddy current sensor (ECS) intregated in mechanisms

Magnetic Fast Steering Mirror (MFSM)

M-FSM Performance With Ø10 mm mirror On 31/12/2019



Parameter	Unit	Value
Angular stroke max	mrad	+/- 34
FS Bandwidth	Hz	250
Mirror stroke @200Hz	mrad	+/- 34
1 st resonance frequency	Hz	116
Resolution	µrad	2-5
Resistance @ 20°C (incl. cables)	Ohm	0.5
Inductance @20°C	mH	0.64
Max drive voltage	V	24
Max drive current	А	10
Dimensions	mm	Ø62 x H56
Total weight	gr	400



Eddy current sensor (ECS) intregated in mechanisms

- Beam Steering Actuator (BSMA)
- IASI-NG : Infrared Atmospheric Sounding Interferometer New Generation
- Customer CNES Prime Contractor Airbus DS
- Earth observation for numerical weather prediction, atmospheric chemistry and climate monitoring in the 2020 to 2040's.
- Mechanism qualified.
- 5 flight models delivered to AIRBUS DS.
- ECS sensors from CTEC will fly.



Interferometer's beam splitter orientation









COTS spatialization thanks to CNES and ESA



- As a result, CTEC technology has been successfully applied in space field for various functions:
- Position proximity sensors.
- End of stroke detection.
- Rotation counting / teeth counting.
- The conditioner is integrated together with the sensor and has been designed to be spatialized.
- Standalone space product.
- Next steps ?
- Tangential motion sensing ?





CTEC proximity current sensor: principle (On/Off sensor)

- › Differential measurement with:
- 1 emitting coil
- 2 receiving coils
- > 1 fixed target
- > 1 moving target
- Technology based on eddy current, working at high frequency (typ. 1 MHz)





R&T CNES PROXIMITY SENSOR : prototype









R&T CNES PROXIMITY SENSOR : performances

Trigger distance

- >1 mm
- Repeatability : +/- 0.1mm
- Hysteresis : < 0.1mm

> Dynamic perf.

- Response time < 1ms
- Target speed < 100mm/s

> Electrical perf.

- Voltage : 3V3 or 5V
- Power consumption < 100 mW
- Output : low <0.4V, high > 0.9V

> Dimensions

- Mass < 11 g
- Size : Ø15mm x 26mm
- Harness : 0.1m to 5m
- > Environment
 - **Op.:** -55°C / +90°C
 - Non Op. : -65°C / +100°C
 - Radiation : 100 kRad
 - Vacuum : 10⁻⁹ Torr



Top Tour proximity sensor

- Sensor based on:
- 1 emitting coil
- 2 receiving coils
- Differential detection
- Eddy currents
- > PCB printed coils
- > 2 sensors for redundancy





Top tour proximity sensor





Top Tour on Euclid mission

- > ESA Euclid telescope (launch 2022)
- Cryo mechanism (CM) used for rotating the filter wheel assembly (FBA) and the grism wheel assembly (GWA), with an open loop stepper motor.
- Top tour FM position sensor provided by CTEC for position reference.









Top Tour on VESUV

- > ESA M5 EnVision mission
- VenSpec-U instrument (VeSUV)
- Top Tour BBM sensor delivered to IRAP.







Top Tour on Theseus mission

- > ESA M5 Theseus mission
- XGIS instrument (X-Gamma rays Imaging Spectrometer)
- Top tour BBM detector for a 7position filter wheel







What about your projects ?

- > What kind of proximity sensors do you need for your projects ?
- > What key specifications are you looking for ?

Thank you for your attention

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