

Project – 2 way communication

Final Presentation

09/11/2023



Schedule

Tuesday 09/11/2023	09:30 – 09:40 10'	Intro & agenda	TASF
	09:40 – 09:50 5'	Project Summary – Use Cases	TASF
	09:50 – 10:00 10'	Project Summary – Protocol & Algorithm design	TASF
	10:00 – 10:10 10'	Project Summary – Testbed experimentation & Security analysis	Qascom
	10:10 – 10:30 20'	WP4 output - Recommendations for a space-based two-way system	TASF
	10:30 – 10:40 10'	WP4 output - Adaptation of two-way ranging to commercial technologies	TASF
	10:40 – 10:50 10'	Conclusion & Way Forward	TASF
	10:50 – 11:30 30'	Discussion	

Project Summary - Reminder



Use Case analysis

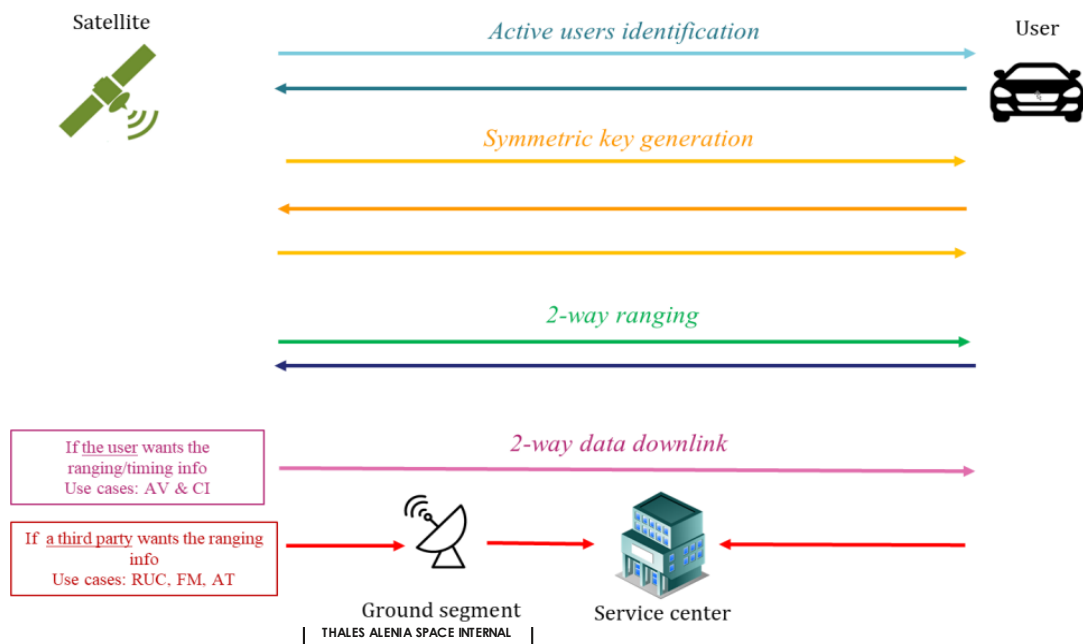
	Autonomous vehicle	Asset tracking	RUC	Fishing monitoring	Critical infrastructure
Nb of users (2024)	225 k	10 k (active)	10 M	25 k	25 k
Nb of users (2029)	10 M	10 k (active)	10 M	50 k	25 k
Density	Specific, see [RD1]	Uniform	Specific, see [RD1]	Specific, see [RD1]	Follow pop. density
Value between two PVT verifications	10 s N/A	1 min	2 min	30 min	5 s
Mode of operation	Waypointing Bootstrapping	Waypointing	Waypointing	Waypointing	Waypointing
Pmd	$10^{-7}/h$	$10^{-4}/h$	$10^{-3}/h$	$10^{-3}/h$	$10^{-5}/h$
Pfa	$10^{-5}/h$	$10^{-3}/h$	$10^{-5}/h$	$10^{-5}/h$	$10^{-3}/h$
TTA	6 s	15mn	15 min	15 min	6 s
Ranging/Timing accuracy	10 m	25 m	100 m	100 m	240 ns (5G)
Reference environment	Light urban	Light urban	Light urban	Open sky	Light urban
Additional sensors	IMU, cameras, lidars, radars, LTE/5G positioning	RFID tags	(LTE/5G positioning)	-	(Internal clock)

Protocol design

- Literature of Distance-Bounding protocols : robustness to Distance-Decrease attacks
 - RTT measurement robust to Distance-Decrease
 - Multi-RTT position robust to Distance-Decrease

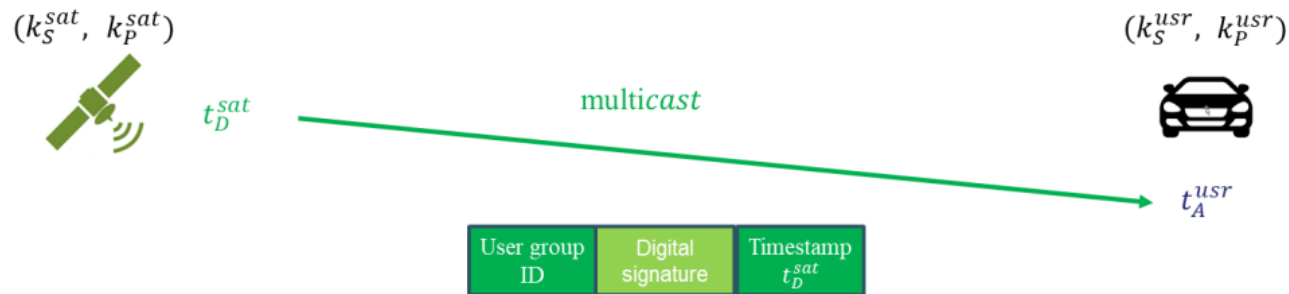
- Tradeoff : satellite-initiated VS user-initiated
 - Satellite-initiated selected
 - Adoption of Downlink Multicast

➤ Protocol steps :

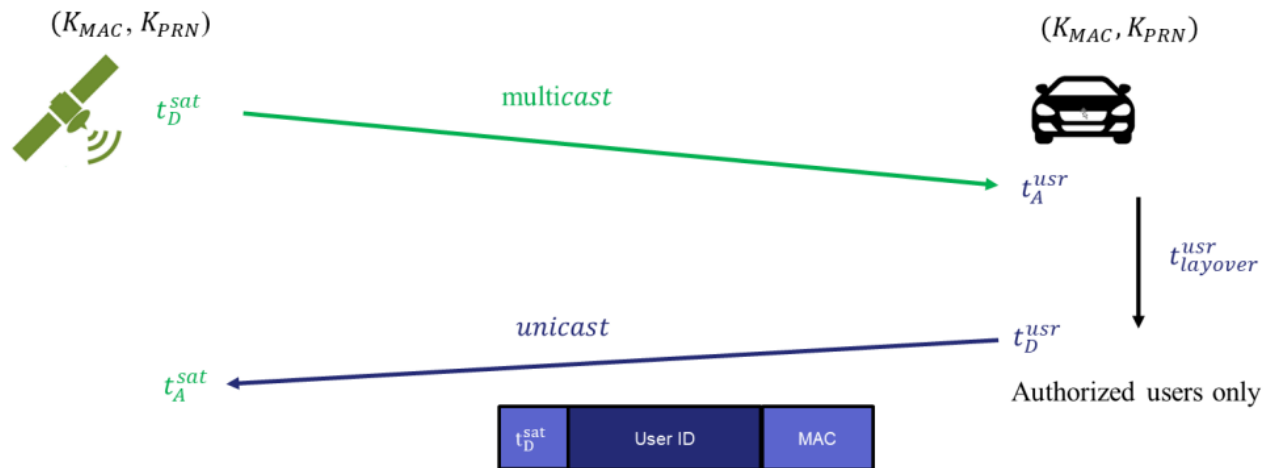


Protocol design – Two-Way Exchange

➤ Downlink request



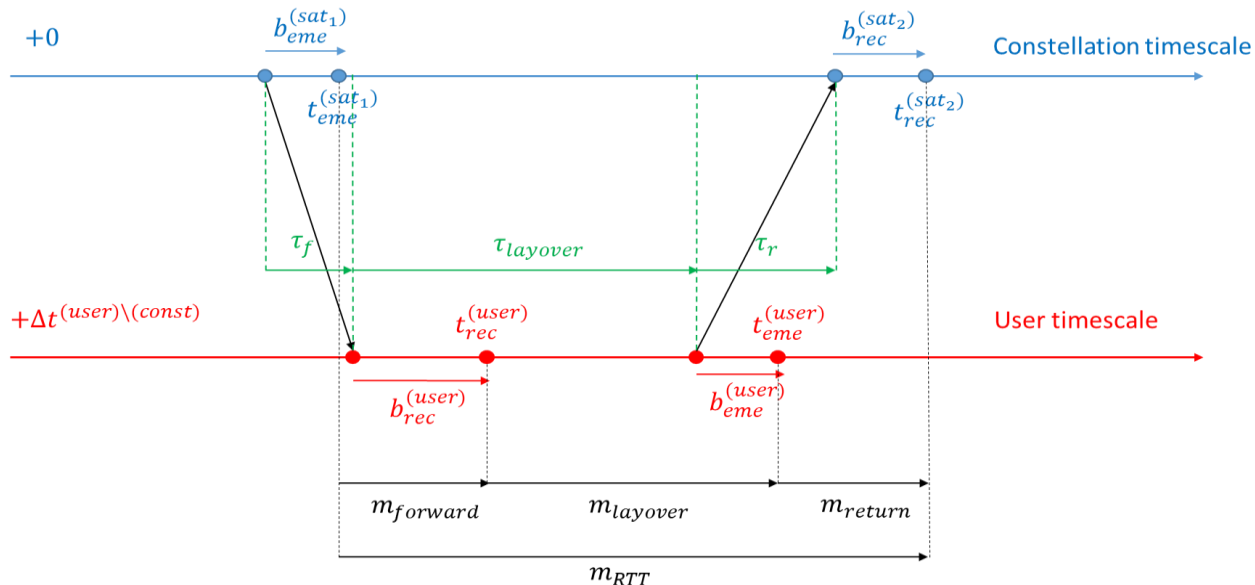
➤ Uplink response



➤ Signal : 1 Mcps, BPSK, Encrypted Spreading code

Measurements output of protocol

➤ Overview of two-way protocol measurements

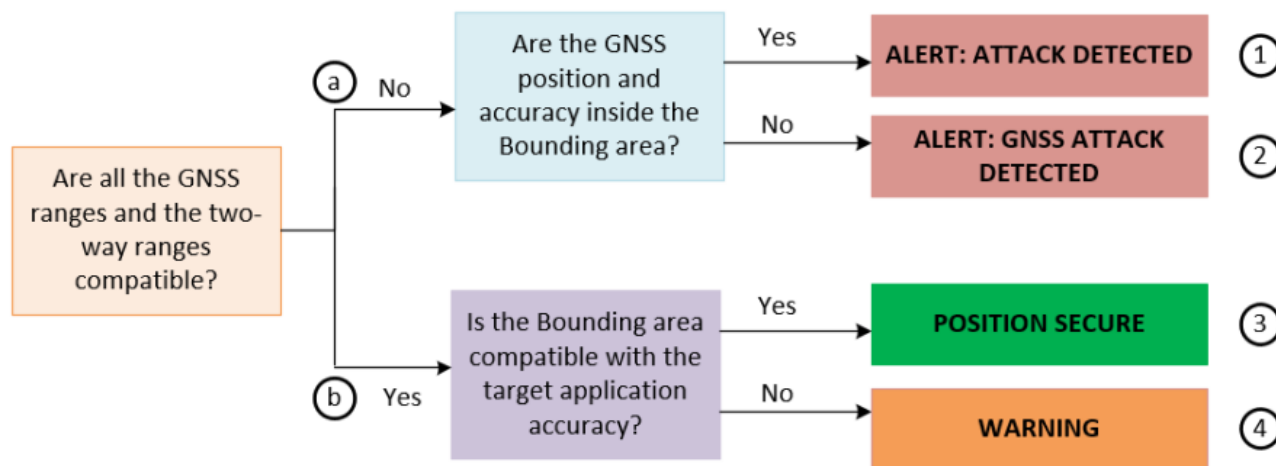


➤ 2 measurements :

- RTT : $m_{RTT} = t_{rec}^{sat} - t_{eme}^{sat}$
- Synchro : $m_{sync} = \frac{1}{2} (t_{rec}^{user} - t_{eme}^{sat} + t_{eme}^{user} - t_{eme}^{sat}) - \delta\tau_{forward\setminus return}$

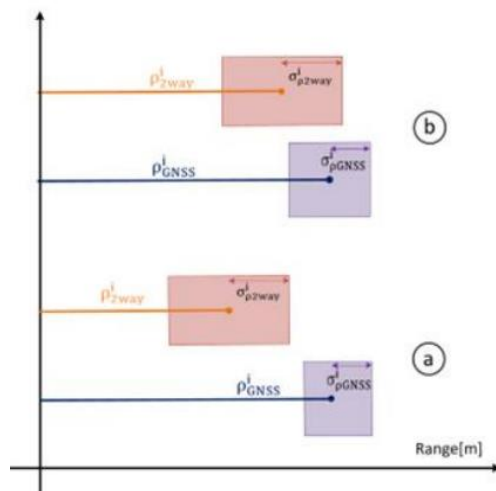
Position verification algorithm design

- Multi-RTT Snapshot Algorithm based on DB protocol
- Single primary satellite → Common focus of ellipsoids
- Two-Step Approach

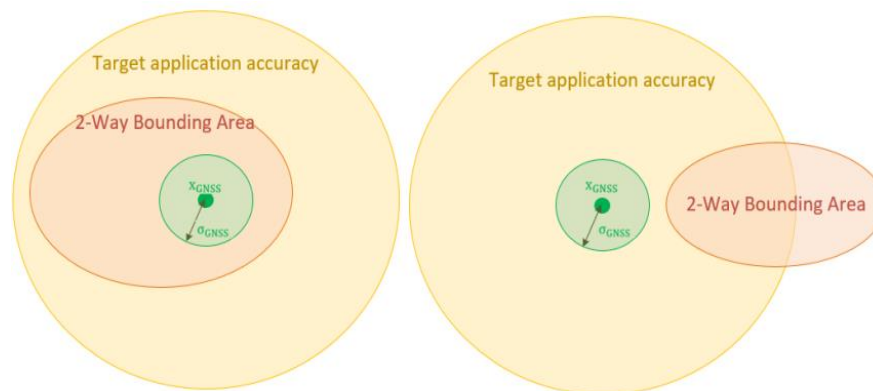


Position verification algorithm design

- Step 1 : position verification – Measurements consistency at reported position

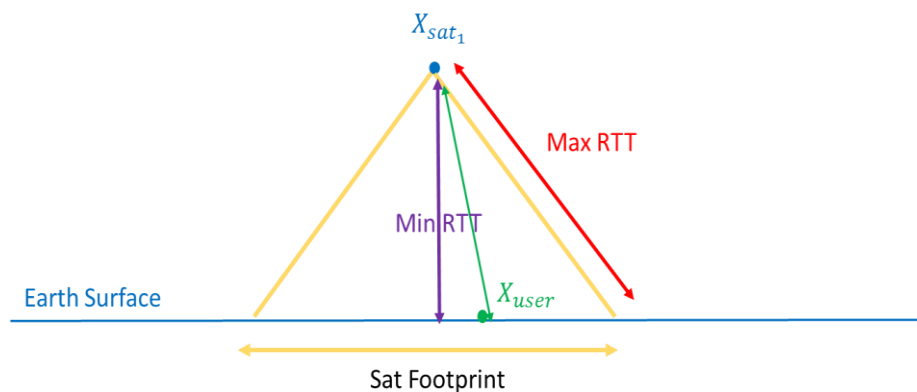


- Step 2 : position computation – Computation of independent bound based on Distance-Bounded RTT



Synchronization Algorithm design

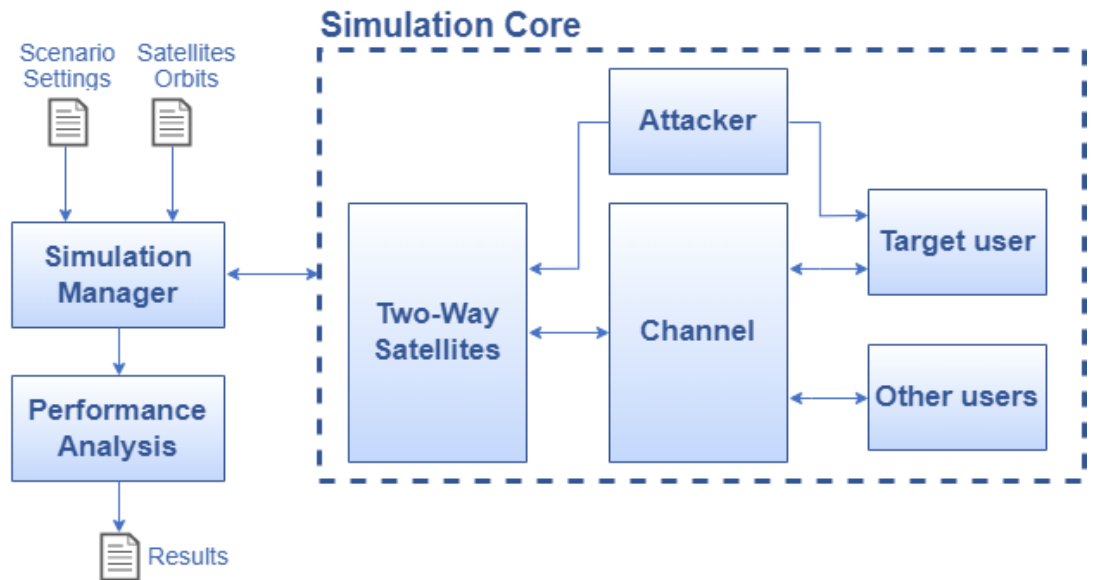
- Computation of maximum possible spoofing delay introduced



- Unknown user position : Uncertainty on computed desynchronization depends on altitude
- Known user position : The RTT can be checked with exact theoretical value

Two-Way Ranging Simulator

- Development of a Matlab simulator
 - Simulation of both positioning and time transfer
 - Compute the KPIs on a single *target user*
 - Simulation of attacks
 - Man in the Middle attack (SCER, Distance Increase)
 - Distance Fraud attacks
 - GNSS attacks



■ Preliminary simulations **Experimentation Plan**

□ Description

- test several short simulations;
- tune the parameters having the higher impact on the KPIs

□ Goals

- assess the sensitivity of the KPIs with respect to the tuned parameters
- define a baseline nominal scenario and a baseline attack scenario

■ Long simulations:

□ Description

- increase the simulation duration;
- test the baseline scenarios and tune the most interesting parameters

□ Goal

- derive statistically meaningful KPIs

■ Nominal scenarios **Experimentation Plan**

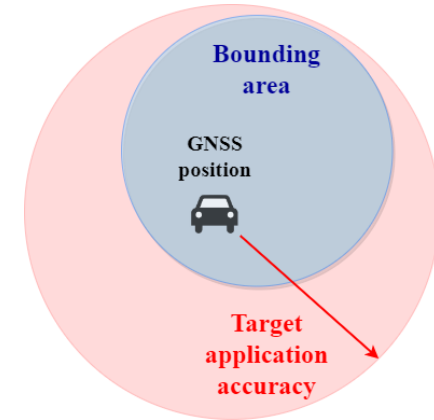
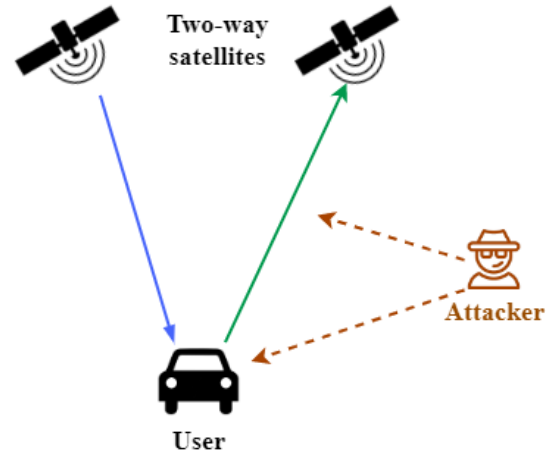
□ Goal

- Authenticate the user GNSS position (positioning mode)
- Authenticate the clock bias (time transfer mode)
- Tune key parameters
- Extract KPIs

■ Attack scenarios

□ Goal

- Detect the attack



Key Performance Indicators (KPIs)

- System availability – A_{system}
 - percentage of iterations the system authenticates the user

- Target application availability – $A_{targetApp}$
 - percentage of times the system authenticates the user within the target application period

- Probability of false alarm – P_{fa}

- Misdetection probability – P_{md}

Testbed Configuration – Nominal Scenario

■ Main tuned parameters:

- User equipment transmitting power P_{UE}
- Time between user requests T_{req}
- Scheduling rule M_{scRule}
- Bandwidth (uplink and downlink) B_w
- Target position accuracy x_{acc}
- LEO satellite constellation SV_{const}

Constellation name SV_{const}	#sat	Satellite altitude [km]
a)	900	1200
b)	300	1200
c)	375	2000
d)	450	2000

- Number of simultaneous Uplinks for the selected simulations : 100

Positioning Mode – Nominal Scenario

■ Results Long Simulations (6h duration):

□ No false alarms: $P_{fa} = 0\%$

□ Baseline scenario:

■ $A_{system} = 43\%$

■ $A_{targetApp} = 92\%$

#ID	M _{scRule}	T _{req} [s]	P _{UE} [W]	B _w [MHz]	x _{acc} [m]	A _{system} [%]	A _{targetApp} [%]	P _{fa} [%]
1	1	10	1	2	100	42.82	92.16	0
2	Inf	10	1	2	100	37.29	91.24	0
3	Inf	10	1	1	100	26.12	78.17	0
4	Inf	5	1	2	100	42.06	100.00	0
5	1	5	1	2	100	42.29	99.01	0
6	Inf	20	1	2	100	28.15	53.27	0
7	1	20	1	2	100	44.26	78.42	0
8	Inf	25	1	2	100	5.45	10.20	0
9	1	25	1	2	100	40.51	60.33	0
10	Inf	10	1	2	25	21.85	71.00	0

Testbed Configuration – Attack Scenario

■ 4 types of simulated attacks:

- GNSS attack;
- GNSS + Man In the Middle (MIM) attack;
- Distance Fraud (DF) attack;
- Distance Fraud + GNSS attack

■ Tuned parameters:

- Distance between the true and the spoofed position $d_{spoofed}$
- Uncertainty on the layover time T_{layStd}

Positioning Mode – Attack Scenarios

■ GNSS attacks

- always detected
- incompatibility between authentic ranges and spoofed position

■ GNSS + MIM, DF, GNSS + DF attacks

- detected with low std of the layover time → incompatibility between spoofed ranges and spoofed position
- $P_{md} = 7.02$ with higher uncertainty on layover time → looser compatibility checks → two-way ranges can be compatible

#ID	Attack type	$d_{spoofed}$ [m]	T_{layStd} [ns]	P_{md} [%]
1	GNSS	500	0.289	0
2	GNSS	150	0.289	0
3	GNSS + MIM	500	0.289	0
4	GNSS + MIM	150	0.289	0
5	GNSS + MIM	150	289	7.02
6	DF	500	0.289	0
7	DF	150	0.289	0
8	GNSS + DF	500	0.289	0
9	GNSS + DF	150	0.289	0

■ System availability: **Time Transfer Mode – Nominal Scenario**

□ Impacted by:

- Elevation mask angle → 30°
- Constellation altitude → 4 tuned constellations

□ $A_{targetApp} = 100\%$

Constellation name	#sat	Satellite altitude [km]
a)	900	1200
b)	300	1200
c)	375	2000
d)	450	2000

#ID	SV_{const}	Satellite altitude [km]	δ_c^{max} [ms]	A_{system} [%]
1	a)	1200	2.7	100
2	b)	1200	2.7	100
3	c)	2000	3.8	100
4	d)	2000	3.8	100

Time Transfer Mode – Attack Scenario

- MIM Distance Increase attack

- $\delta_c > \delta_c^{max} \rightarrow$ attack always detected

- Distance Fraud attack

- $\delta_c > \delta_c^{max} \rightarrow$ attack always detected

#ID	Attack type	Link	δ_c [ms]	P_{md} [%]
1	MIM - DI	Uplink	3.85	0
2	MIM - DI	Downlink	3.85	0
3	DF	Uplink	3.85	0

Recommendations for a space-based system dedicated to two-way



Constellation geometry

- Testbed showed that essential parameters are :
 - Number of satellites in visibility instantaneously
 - Primary satellite elevation
 - Geometric diversity between secondary satellites

- Retained constellations
 - ≥ 450 satellites / ≥ 2000 km altitude
 - Hypothesis : random selection of primary satellite

- Promising constellations : MEO + LEO
 - Primary satellites at MEO → High elevation (+ No UL budget problems)
 - Secondary satellites at LEO → Low elevation

- Possible adaptation of protocol for constellation optimization
 - ➔ Selection of primary satellite at user level
 - Better geometry → Reduction of constellation size
 - Simplification of allocation plan

Payload Design – Satellite onboard computation needs

➤ Recall of session rate for 1200km satellite

	Total nb of active users in 2029 (k)	Tx duration (s)	Tx period (min)	Nb of signals simultaneously transmitted in a sat footprint
Autonomous vehicles (bootstrapping)	700	1.2	8h	44
Road user charging	70		15	93
Asset tracking	10		10	20
Fishery monitoring	50		30	33
Critical infrastructures	25		5	100
TOTAL	855			290
Target				280

➤ Extrapolation to 2000km altitude → 384 /s

➤ Main operations performed onboard

- Acquisition / Demodulation of 384 AUI Uplinks /s
- Acquisition / Demodulation of 384 Uplink responses /s

➔ 1 Versal Core Processing board (50W)

Payload Design – Satellite Downlink transmission power

➤ Downlink Data Stream

- Downlink requests → 460bps (1 request each 1.2s)
- Two-Way Data Downlink → 61.6kbps - **268b per user of AV / CI**

➤ Downlink Budget analysis

- Omni-directional transmission within the footprint
→ **100W Transmission Power**

➤ Two-Way Data Downlink is unicast → Use of SDMA w DL Beamforming

- 7 beam – uniform power accross beams
→ **14W Transmission Power**

➤ Beamforming allows

- Sufficient UL demodulation probability under Intra-syst. Interference
- Reduced DL transmission power

Payload Design – Tentative payload Size / Weight / Power

- Estimated required power for 2 scenarios
 - Omnidirectional Downlink Transmission
 - Downlink SDMA

		Power consumption - Omni (W)	Power consumption - Beamforming (W)
Rx GNSS		10	10
2 way	Processing :	50	50
	- 1 Versal core processing board		
	- 1 timing board		
	RF :	200	30
	- 1 Front-end RF Tx (100W / 15W RF)		
- 1 Front-end RF Rx			
Filtering	0	0	
Margin (%)	20	56	18
Total		336	108

- Benchmark Solution → GOMSpace 16U
 - 12U Payload size
 - 80W-150W Average power
- ➔ 16U estimated for beamforming solution
- ➔ Towards micro-satellite (80kg) for Omnidirectional DL

Recommendations on revisit time

- Revisit time = max. duration between 2 station visibilities
- Revisit time dimensioning for
 - Compliance to TTA requirement for remote users
 - Required onboard memory (secondary)
- Revisit time dimensions TTA of monitoring use cases
 - Information transits through ground segment
 - Target TTA value : 15mn → Asset tracking / IUU Fishing / RUC
- Target revisit time depends on ISL in system design
 - No ISL → Revisit time = 15mn
 - ISL → 15mn = transit time through ISL to ground segment
- Estimated onboard memory needs
 - 52kbps memory input
 - 47Mb for 15mn revisit time

Recommendations on satellite footprint

- 2000km, 30° elevation mask
 - ➔ Fp area 14M km² - **460 simultaneous Uplinks interfering**
 - ➔ Number of users above system capacity assessed in testbed

- Beamforming (7 beams), 30° elevation mask
 - ➔ Beam area 1.9M km² - **70 simultaneous Uplinks interfering per beam**
 - ➔ Number of users coherent with capabilities demonstrated in testbed

- Elevation mask of 30° considered due to environmental conditions of most use cases

- Beamforming hypothesis requires antenna area of :
 - 0.73m² for considered L-band hypothesis
 - 0.17m² for retained S-band in ELCANO dedicated to Two-Way

- ➔ Preferred solution : shifting to higher frequency band (S-band) and have a satellite multi-antenna

Envisioned Way Forwards – System sizing

- Study the extension to **multi-epoch** of the Distance-Bounded RTT positioning / position verification
 - Extend positioning concept to multi-epoch
 - Possible use of IMU
 - Relax attack hypotheses (LOCFIT)
 - Extend position verification concept to multi-epoch
 - Verification of sequence of positions (LOCFIT)

- ➔ Enable two-way positioning with smaller constellations

- Study of **LEO + MEO** constellations
 - Assessment of two-way positioning performance with LEO + MEO
 - Cost Analysis / Optimization

Envisioned Way Forwards – System sizing

➤ Protocol improvements (ELCANO)

- Enable online selection of primary satellite at user level
 - Simultaneous Downlink transmission on all satellites
 - Satellite ID information in return Uplink
- ➔ Better geometries and position availability
- Random selection of session (ALOHA Uplink Multiple Access)
 - Reduce allocation plan complexity
 - Avoid an Active Users Identification phase
- ➔ Reduced UL / DL datarates
- ➔ No need for allocation plan
- Adaptations of the waveform (single-PRN DL/UL)
- **Followup activity** : Perform security analysis of this concept

Adaptation to commercial technologies



- The protocol designed in the context of the study i
 - No existing system / user device for this protocol

- Study possibility to use standardized protocol as a support for two-way
 - Derive requirements for a protocol that supports two-way
 - Identify candidate protocols
 - Derive modifications of the associated user device

- Protocols considered
 - LoRa CSS
 - LoRa LR-FHSS
 - Argos
 - Nb-IoT
 - LTE-M
 - VDES
 - E-SSA
 - 5G NR

Requirements for a protocol that supports two-way

- R1 – Bidirectional communication
- R2 – Wide-band for Uplink & Downlink
 - Def : >2MHz bandwidth (derived from testbed result)
- R3 – Secure physical layer
 - Def : Short symbols for robustness to SCER, >1 μ s length
- R4 – Waveform robust to LEO Doppler
- R5 – No reliance on user position / synchronization
- R6 – Communication with multiple satellites

Benchmark protocols wrt requirements

➤ LoRa CSS

- Vulnerable physical layer (Long symbols)
- Doppler pre-compensation (initial pos. / sync. necessary)
- Single-satellite communication

➤ Nb-IoT

- Narrow-Band (200kHz max)
- Doppler pre-compensation (initial pos. / sync. necessary)
- Single-satellite communication

➤ LTE-M

- Doppler pre-compensation (initial pos. / sync. necessary)
- Single-satellite communication

➤ Argos

- Narrow-Band (50kHz)
- Vulnerable physical layer (long symbols)

Benchmark protocols wrt requirements

➤ LoRa LR-FHSS

- Narrow-Band (Max. 488Hz baseband BW)
- Vulnerable physical layer (Long symbols – 325bps max)

➤ VDES

- Narrow-Band (Max. 150kHz)
- Vulnerable physical layer (Symbol duration >5ms)

➤ E-SSA

- Doppler pre-compensation (initial pos. / sync. necessary)
- Single-satellite communication

➤ 5G NR

- Doppler pre-compensation (initial pos. / sync. necessary)
- Single-satellite communication

Adaptation of commercial user devices

- No standardized protocol supports the designed two-way protocol

- Operations performed at tracker level
 - Cryptographic operations :
 - key exchange with KMI
 - verification of DL request signature
 - UL response MAC generation
 - UL / DL Encrypted PRNs generation
 - Active users identification ping reception
 - Acquisition / demodulation of Downlink request
 - Precise control of Layover time between DL / UL
 - Transmission of Uplink response

- No identified COTS performs these operations
- ➔ Perspective in prototyping user device

Envisioned way forward

Point : Difficulty to overlay Two-Way on standardized protocol / existing COTS

- Consolidate protocol output of ELCANO project
- Consolidate complexity assessment of user segment
 - Transmission power reasonable
 - Still to be analyzed for constraints imposed by accurate layover time
- Implement first prototypes of user devices