PROTOTYPE OF K/S-BAND GROUND STATION ANTENNA

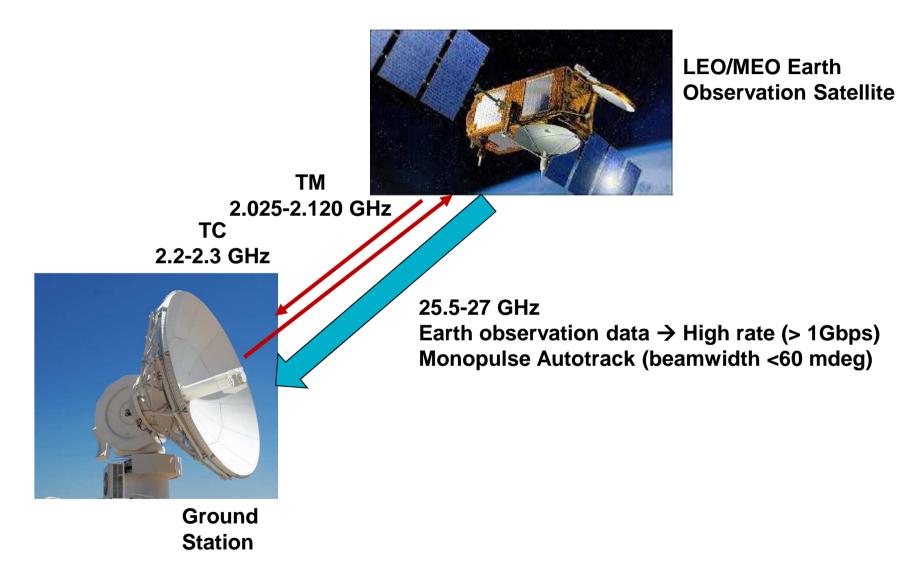
(GSTP REF. G511-0035GS)



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INTRODUCTION



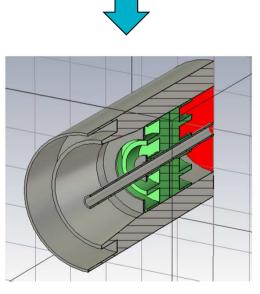
INTRODUCTION

- Prototype of K-Band Ground Station Antenna target requirements
 - K-band, downlink: 25.5 27 GHz
 - S-band, uplink: 2.025 2.120 GHz
 - S-band, downlink: 2.2 2.3 GHz
 - Polarization: RHCP and LHCP in both bands
 - High antenna efficiency > 70%
 - Antenna directivity K-band ≥ 60.5 dBi
 - K-Band G/T ≥ 37.5 dB/K
 - Pointing accuracy: 0.035° (up to100Km/h wind)
 - Low axial ratio (<1 dB in S band / <0.5 dB in K band)</p>
 - Monopulse tracking at K-band capable of tracking linear or circular polarization signals. The feed system has two tracking waveguide ports
 - Tracking accuracy: better than 5% of θ-3dB
 - Reflector illumination compatible with ITU Recommendation S-732
 - Reflector surface panel 0.1mm total reflector <0.25mm RMS</p>



Dual Band Feed Horn

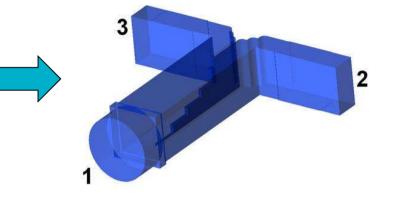
- Two horns one inside the other
 - Inner one \rightarrow high frequency standard open waveguide horn
 - External one \rightarrow coaxial horn aperture with corrugations



Model simulated with CST to improve tunning and side lobes in both bands



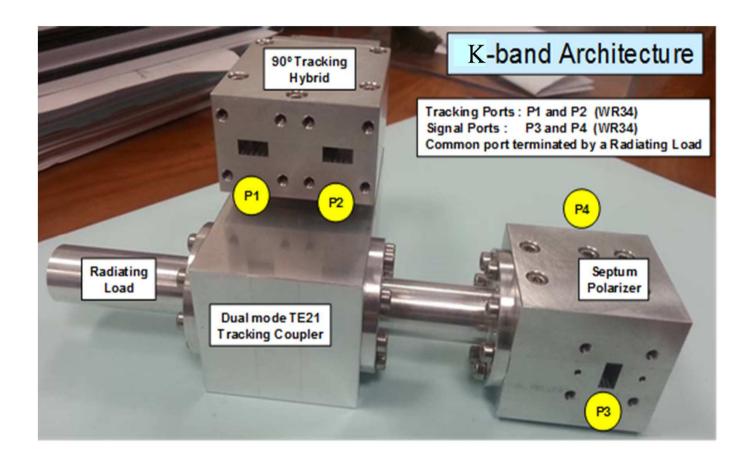
- K-band Section (I)
 - OMT-Septum Polarizer
 - Three step thin septum
 - WR34 for RHCP and LHCP ports



- Dual TE21 Resonant Tracking Coupler
 - Oversized circular waveguide + under-cutoff waveguide + coupling slots
 - Direction of the slot depends on the higher mode
 - Two resonant structures (to work in both polarizations)
 - Combination of coupled modes \rightarrow 90° Hybrid coupler
 - 8% bandwidth achieved
 - Size: 160x142x74 mm

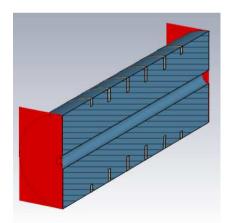


K-band Section (II)

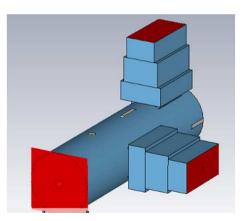




- S-band Section
 - Corrugated polarizer
 - Convert orthogonal linear polarized signals to circular polarized
 - OMT
 - Separates the two orthogonal linear signals
 - Two slots coupled T-junctions
 - Septum to separate the T-junctions
 - WR340 ports for Tx and Rx (RHCP and LHCP)



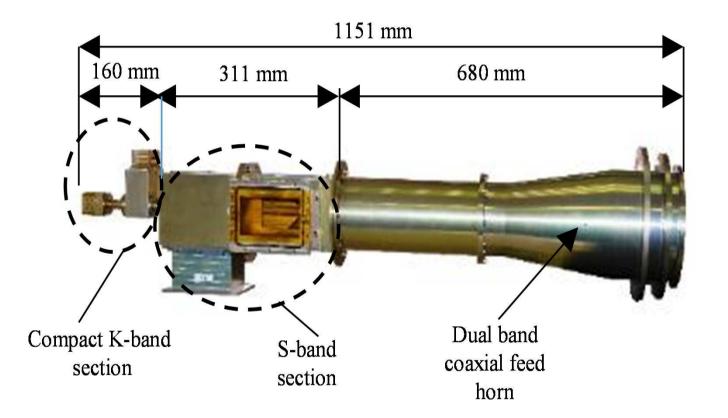
Corrugated polarizer



OMT

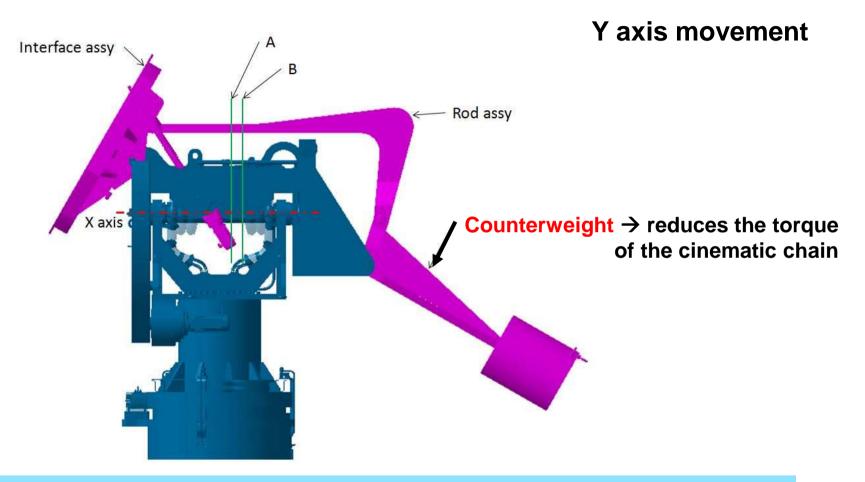


Manufactured K/S-Band Feed





The Positioner mechanical concept based on a 2-axes tracking system (X and Y) with a third axis (Z) to place strategically the X-Y gimbal, minimizing the axes speed

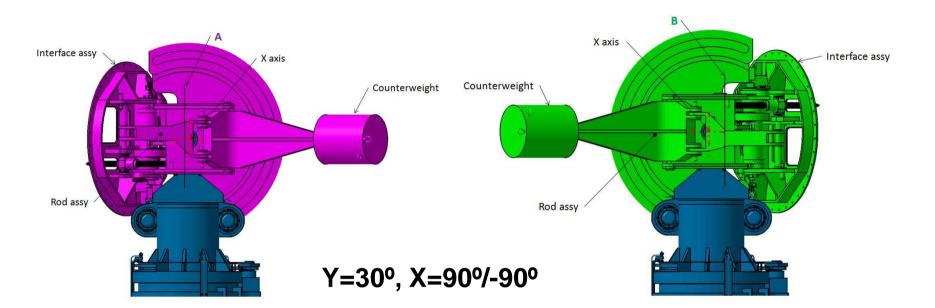


Thanks to the counterweight, during Y axis rotations (from 95° to -10°) pink colour system COG is between green lines A and B, and as close as possible to X axis.

The change up/down is: Y90=79.2 mm, Y0=96.8 mm.

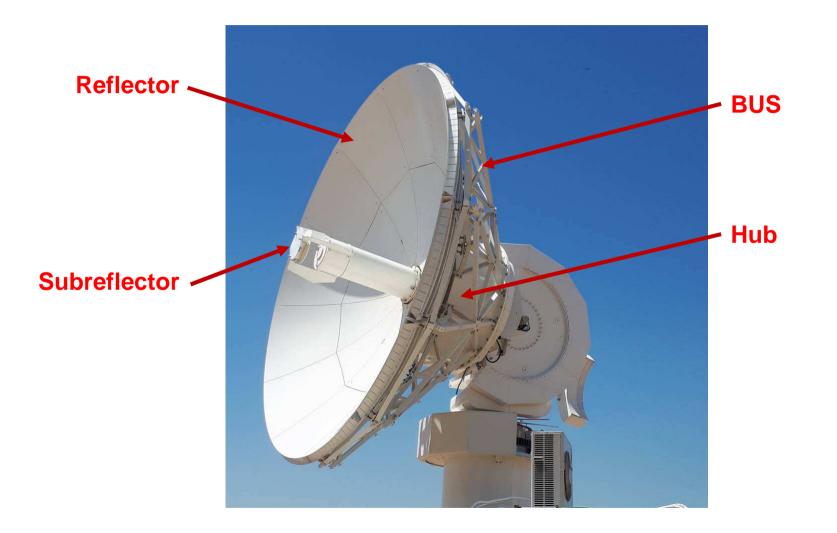


X and Y axes combined motion

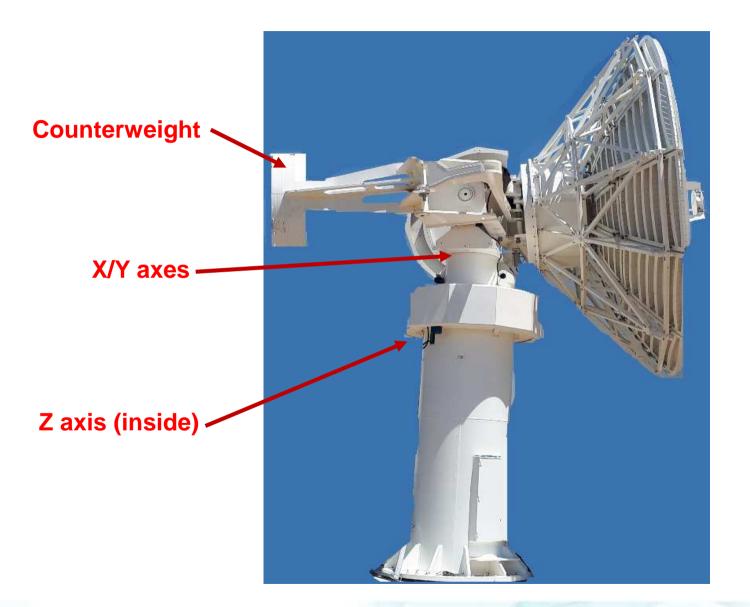


For combined motion of X and Y axes, the aim of the Counterweight is to equilibrate the system during this combined rotation. In this case the CoG is between green lines A and B, and as close as possible to X axis











 The antenna HUB has a considerable size allowing to host K-Band components including down-converters as close as possible to the LNAs.



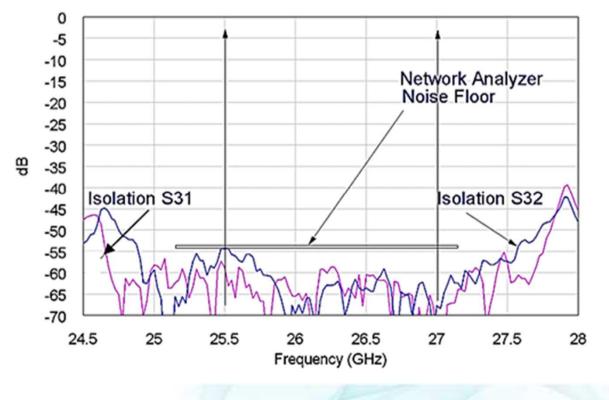


SERVO Subsystem main features:

- Controls the antenna motion, limiting the acceleration and velocity of each axis.
- Guarantees the safety of the motion, by means of several travel limits, emergency pushbuttons and interlocks distributed along the Positioner structure and Servo Drive Cabinet.
- Implements several tracking strategies: Program Track and Autotrack (feedback of error signals received from the Tracking Receiver)
- Interfaces with the Monitoring and Control System in order to accept motion commands and returns the servo system status.



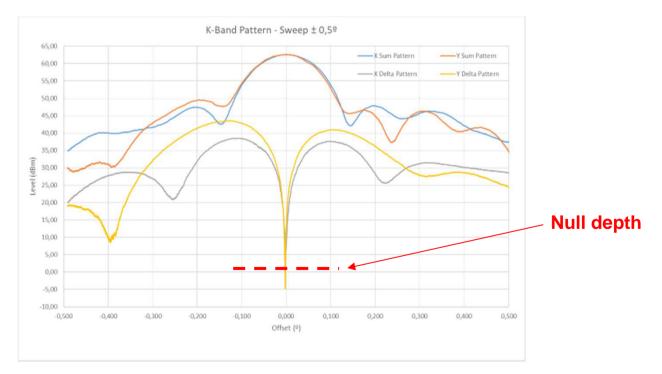
- K-band (I)
 - Feed Isolation
 - P3-P4 Isolation > 28 dB
 - P3-P1 Isolation > 55 dB → Negligible Crosstalk, ideal for monopulse tracking



- K-band (II)
 - Feed Insertion Losses
 - Better than -0.18 dB
 - Feed Return Losses
 - S33, S44 < 20 dB
 - S11, S22 < 20 dB
 - Antenna Directivity and G/T
 - Antenna directivity ≥ 63.1 dBi
 - G/T ≥ 36.1 dB/K (with nominal configuration, derived from measurements)
 - Axial Ratio
 - < 0.55 dB (Feed including radome window)</p>
 - Outdoor measurement not valid due to the calibration tower
 - Pointing Accuracy
 - Sigma 6.7 mdeg
 - Adjusted with Sun and GEO satellites in several iterations



- K-band (III)
 - Sum and Delta Radiation Patterns
 - Side lobes > 15 dB
 - 3 dB Beamwidth: 0.116°@25.5 GHz and 0.113°@27 GHz
 - Null depth higher than 45 dB → ideal for monopulse tracking



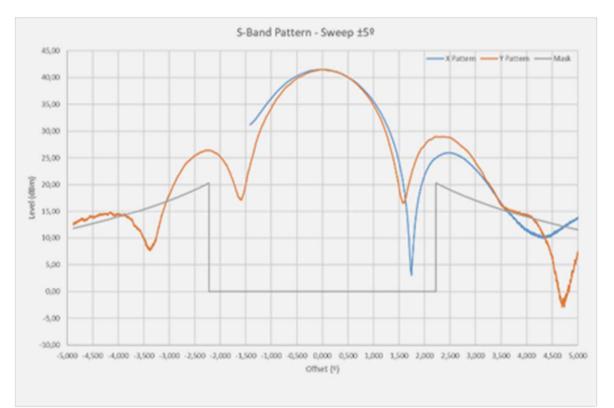


- S-band (I)
 - Feed Isolation
 - Signal ports > 20 dB
 - Feed Return Losses
 - Better than -20 dB
 - Feed Axial Ratio
 - < 1 dB
 - Antenna Directivity and G/T
 - Antenna directivity ≥ 41.9 dBi
 - G/T ≥ 18.3 dB/K (theoretical with nominal configurations, derived from measurements), ≥ 20.4 dB/K (theoretical reception only)



MEASUREMENTS

- S-band (II)
 - Radiation Patterns
 - Side lobes > 15 dB
 - 3 dB Beamwidth: 1.4°@2250 MH



CONCLUSIONS

Project innovations in different knowledge domains

- Innovative dual S/K Band feed solution coaxial feeder where inner horn provides K-band and outer horn provides S-band. Including monopulse autotrack.
- Antenna reflector. Innovative manufacturing process for the antenna reflector with vacuum forming and bonded panels (to be executed within Spanish industry)
- X/Y/Z Innovative positioner solution. High precision mechanical design able to work in K-band frequency and keep pointing accuracy with such narrow beamwidth.
- Design to cost. Design to cost efficient ratio, developing a solution

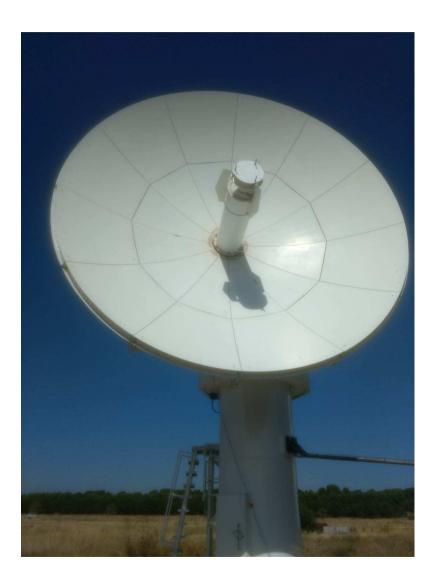


CONCLUSIONS

- Main achievements:
 - Novel compact simultaneous K/S-band feed for next generation of Earth Observation ground stations
 - Positioner X/Y/Z, minimizing the axes speed in LEO/MEO applications.
 - Excellent K-Band radioelectrical performances (0.118 deg at 3 dB beamwidth; antenna directivity ≥ 63.1 dBi)
 - G/T ≥ 32 dB/K (measured with limited LNA performances, and no downconverter gain)
 - Reflector surface accuracy < 0.085 mm RMS</p>
 - 2 channel monopulse with a Tracking null depth \geq 40 dB



CONCLUSIONS



6 meter K/S-band tracking antenna for LEO/MEO applications

K-Band receive and monopulse Tracking chains

S-Band transmit and receive chains for Telemetry and Telecommand

X/Y/Z Positioner (no limitation for high elevation satellite passes and minimum axes velocity)





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